Filter Banks – II

Multi-Rate Signal Processing

Dr. Yogananda Isukapalli

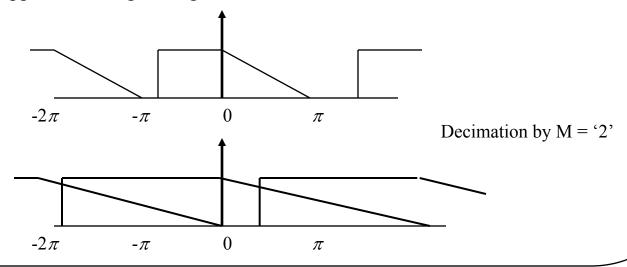
Concepts of Multi-Rate Signal Processing:

1. <u>Decimation:</u> Sampling rate reduction by integer factors after band-limiting the input signal

The sampling rate of a sequence can be reduced by "sampling" it, i.e. by defining a new sequence

$$x_{\rm d}[n] = x[nM] = x_{\rm c}(nMT)$$

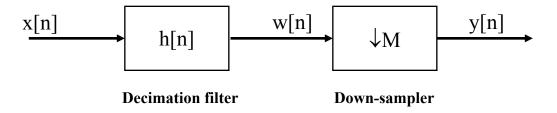
The Sampling rate compressor reduces the sampling rate from F_s to F_s/M . In frequency domain, it is equivalent to multiplying the original signal band-width by a factor M. Hence, if the signal is not band-limited to π/M , down-sampling results in aliasing as shown in this following Example. If this happens, the original signal cannot be recovered from the decimated version.



Avoiding Aliasing:

Aliasing can be avoided if x(n) is low-pass signal band-limited to the region $|w| < \pi / M$..

In most applications, the down-sampler is preceded by a low-pass digital filter called "decimation filter"



To prevent aliasing at a lower rate, the digital filter h[k] is used to band-limit the input signal to less than $F_s/2M$ beforehand. Sampling rate reduction is achieved by discarding M-1 samples for every M samples of the filtered signal w[n].

$$y[n] = w[nM] = \sum_{k=-\infty}^{\infty} h[k].x[nM-k]$$

2. <u>Interpolation:</u> Sampling rate increase by integer factors followed by anti-imaging filter.

Interpolation is the digital equivalent of the digital-to-analog conversion where the analog signal is recovered by interpolating the digital samples applied to the D/A converter. In the case of Digital interpolation, however, the process yields specific values.

Interpolator:

Sampling Rate Expander x(n)Fs

LFs

Interpolation by a factor of 'L' y(n) h[n]LPF h[n]LFs

Sample Rate Expander : For each sample of x[n], the expander inserts L-1

zero-valued samples to form a new signal w[n].

Anti-Imaging filter : Low pass filter removes image frequencies created by

the rate increase to yield y[n].

The input-output relationship is:

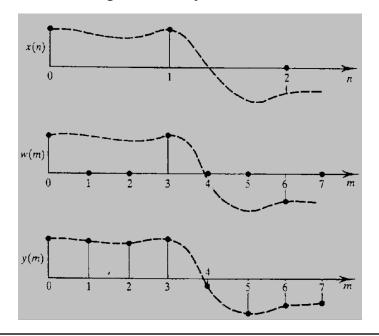
$$y[n] = \sum_{k=-\infty}^{\infty} h[k].w[n-k]$$

where,

$$w[n]$$
 = $x[n/L]$ $n = 0, \pm 1L, \pm 2L, \pm 3L, ...$
otherwise.

Example:

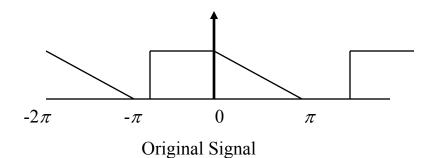
Time domain illustration of interpolation by a factor of L = 3.

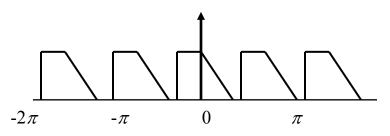


Spectral interpretation of interpolation:

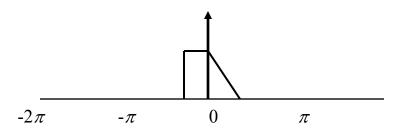
Note:

- * This has the effect of compressing the frequencies occupying the band from 0 to $L\pi$.
- * Upsampling and interpolation are <u>not</u> equivalent. Interpolation requires an additional lowpass filter with a cut-off frequency of π/L to eliminate images of the signal





Output of Upsampler



Output of Interpolation (after passing through Anti-imaging filter)

Sampling rate conversion by non-integer factors.

In some applications, the need often arises to change the sampling rate by a non-integer factor.

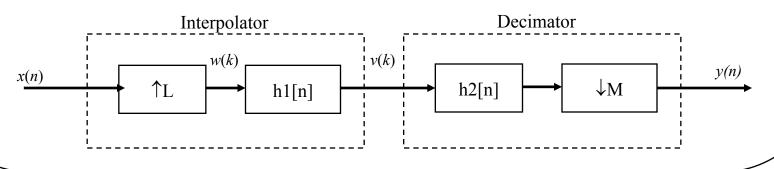
Ex:- Transferring data from Compact Disc system at rate of 44.1 kHz. to a Digital Audio Tape (DAT) at 48 kHz. This can be achieved by increasing the data rate of the CD by a factor of 48/44.1, a non-integer

Approach:

The non-integer factor is represented by a rational number, i.e.a ratio of two integers, say L and M, such that L/M is as close to the desired factor as possible. First interpolation by factor L is done, followed by decimation by a factor of M.

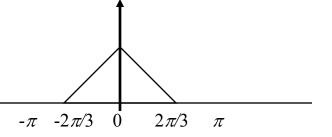
* Interpolation precedes Decimation. Why?

Decimation removes some of the desired frequency components.

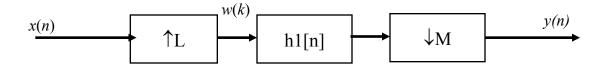


Example:

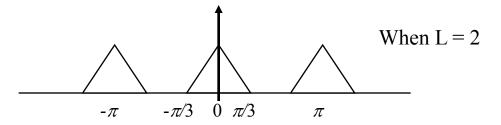
Consider a bandlimited (to $2\pi/3$) signal.



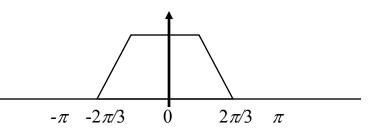
Let us select the Interpolation factor L = 3, decimation factor M = 2 so that resultant conversion factor is L/M = 3/2 = 1.5. Consider the following multirate system.



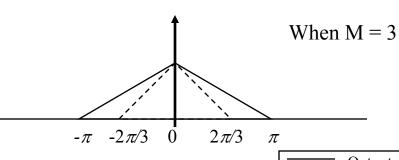
Upsampling by L = 2 compresses the bandwidth by factor of "2" and creates images



If we carefully select the frequency characteristic of the filter h(n) as shown in the figure, we can eliminate the images.



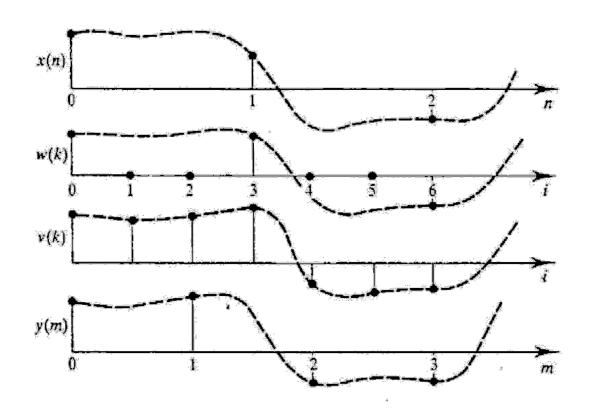
Filtering the upsampled signal by a low-pass filter with cut-off frequency Pi/3 followed by down-sampling by M = 3 increases the bandwidth by factor of "3", without aliasing!



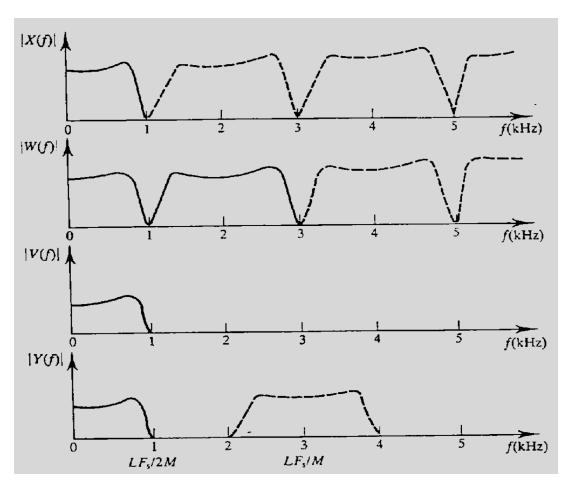
Output signal
Input signal

Example (contd.): Required sampling rate conversion by a factor of "1.5"

Therefore, let Interpolation factor L=3, decimation factor M=2 so that resultant conversion factor = L/M = 3/2 = 1.5



Spectral interpretation of sampling rate increase of a signal at 2 kHz rate by a factor of 3/2. Signal rate first increased to 6 kHz by a factor of 3, then band-limited and then reduced to 3 kHz by a factor of 2.

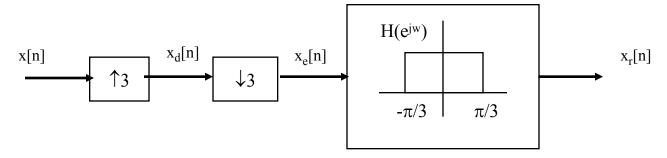


Examples

1. Consider the following system. For the following input signals, determine whether the output is equal to input.

1.
$$x[n] = cos(\pi n/4)$$

2.
$$x[n] = cos(\pi n/2)$$



Solution:

The output $x_r[n] = x[n]$ if no aliasing occurs as result of down-sampling. That is $X(e^{jw}) = 0$ for $\pi/3 \le |w| \le \pi$.

1). Input is: $x[n] = cos(\pi n/4)$

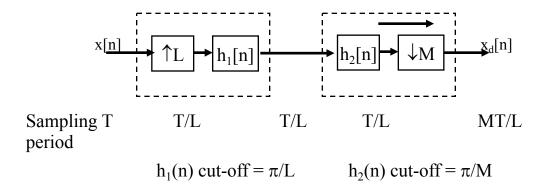
 $X(e^{jw})$ has impulses at $w = \pm \pi/4$. So there is no aliasing i..e. $x_r[n] = x[n]$

2). Input is: $x[n] = cos(\pi n/2)$

 $X(e^{jw})$ has impulses at $w = \pm \pi/2$. and $X_e(e^{jw})$ also has two impulses which are filtered by the filter at the output So there is aliasing i.e. $x_r[n] \neq x[n]$

2.

Given that an input signal $x[n] = \sin(3\pi n/4)$ is applied to the following system, where L = 3, and M = 5. Determine the corresponding output y[n].



Upsampling by 3 and lowpass filtering x[n] results in $sin(\pi n/4)$.

Down sample by 5 gives us that $y[n] = \sin(5\pi n/4) = -\sin(3\pi n/4)$.

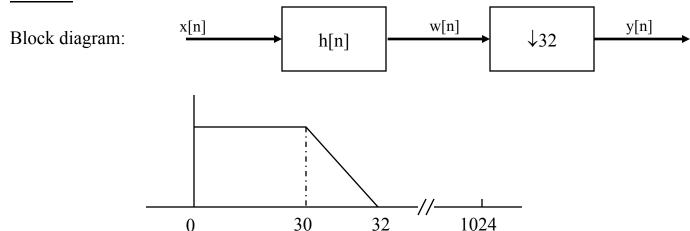
3.

A signal at sampling frequency 2.048 kHz is to be decimated by a factor of 32 to yield a signal at sampling frequency of 64 Hz. The signal band of interest extends from 0 to 30 Hz. The anti-aliasing digital filter should satisfy the following specifications:

| Pass-band deviation | 0.01 dB |
|---------------------|------------|
| Stop-band deviation | 80 dB |
| Pass-band | 0 - 30 Hz |
| Stop-band | 32 - 64 Hz |

The signal components in the range from 30 to 32 Hz should be protected from aliasing. Design a suitable one-stage decimator.

Solution:



The block diagram of the single stage decimator, and the specifications for the lowpass anti-aliasing filter are shown in the figure. From the given specifications,

$$\Delta f = (32-30)/2048 = 9.766 \times 10^{-4}.$$

 $\delta_p = 0.00115$ from $-20\log(1+\delta_p) = 0.01dB.$
 $\delta_s = 0.0001$ from $-20\log(\delta_s) = 80dB.$

An estimate of the number of filter coefficients for the single stage decimator is given by:

$$N \approx \frac{D_{\infty}(\delta_{p}/\delta_{s})}{\Delta f} - f(\delta_{p}, \delta_{s}) \cdot \Delta f + 1,$$
where,
$$D_{\infty}(\delta_{p}/\delta_{s}) = (\log_{10}\delta_{s}) \cdot [a_{1} \cdot (\log_{10}\delta_{p})^{2} + a_{2} \cdot (\log_{10}\delta_{p}) + a_{3}] + a_{4} \cdot (\log_{10}\delta_{p})^{2} + a_{5} \cdot (\log_{10}\delta_{p}) + a_{6}.$$

$$a_{1} = 5.309 \times 10^{-3}; \qquad a_{2} = 7.114 \times 10^{-2};$$

$$a_{3} = -4.761 \times 10^{-1}; \qquad a_{4} = 2.66 \times 10^{-3};$$

$$a_{5} = -5.941 \times 10^{-1}; \qquad a_{6} = -4.278 \times 10^{-1};$$

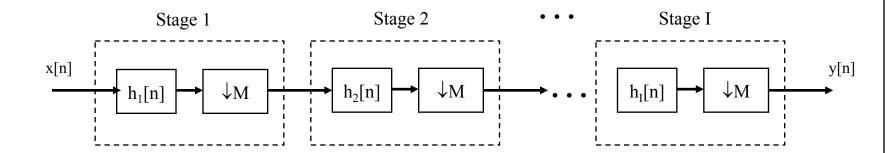
Thus N = 3947. It is quite obvious that N is too large. In fact, none of the available filter design methods can be used to obtain the coefficients for such a filter because approximation errors would be too large. Hence multistage approach to sampling rate conversion is to be employed for all practical purposes.

Multistage approach to Sampling Rate Conversion.

When large changes in the sampling rate are required, it is more efficient to change the rate in two or more stages than in a Single stage.

Advantage:

Allows gradual reduction or increase in sampling rate, leading to significant relaxation in the requirements of the anti-aliasing or anti-imaging filter at each stage.



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Design of Practical Sampling Rate Converters

- specify the overall anti-aliasing or anti-imaging filter requirements and those for individual stages
- determine the optimum no. of stages of decimation or interpolation.
- determine the decimation or interpolation factors for each stages.
- design an appropriate filter for each stage.

Filter specification:

Performance of a multi-rate system depends critically on the type and quality of filter used. Either IIR or FIR filters can be used, but FIR is the more popular as it is computationally effective, as well have desirable features such as linear phase response and low sensitivity to finite word-length effects, as well as simple to implement.

Requirements: For decimation, overall filter requirements, to avoid aliasing after rate reduction are:

Pass-band $0 \le f \le f_p$

Stop-band $F_s/2M \le f \le F_s/2$

pass-band deviation δp

stop-band deviation δs

Requirements: For Interpolation, overall filter requirements are:

Pass-band $0 \le f \le f_p$

Stop-band $F_s / 2 \le f \le LF_s / 2$

pass-band deviation δp

stop-band deviation δs

Number of stages and decimation factors:

Number of multiplications per second MPS = $\sum_{i=1}^{I} N_i F_i$ (F_i - the output sampling frequency)

Total storage requirements TSR = $\sum_{i=1}^{I} N_i$ (N_i- the filter length)

where I is the optimum no. of stages in the multistage design.

Algorithm:

- Specify overall filter parameters.
- For each value of I (= 1,2,3..Imax), obtain all possible set of integer decimation factors M.
- For each set, determine filter requirements, the MPS and TSR.
- For each value of I, select the decimation factors giving the most efficient design in terms of storage requirements.
- Select most efficient or desired solutions.

Application Example

Audio Engineering:

Digital Audio Engineering is an area that has been benefited significantly from Multirate Techniques.

- In A/D conversion process, High quality digital data is obtained from analog data by combining multirate processing with delta modulation techniques
- Simplified the D/A conversion process

Efficient D/A conversion in Compact Disc Players:

Figure depicts the process of reconstituting the analog audio from the digital signal read from CD

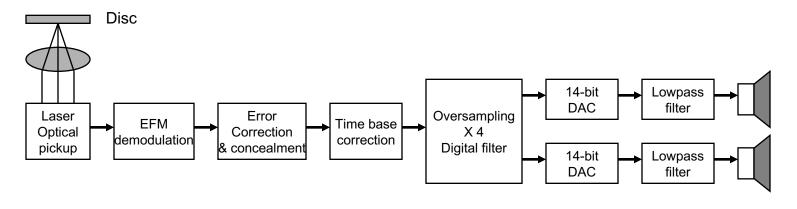


Fig. Audio signal reproduction in Compact Disc System

After decoding, the digital signals are in 16-bit words representing the acoustic information at a 44.1 kHz sampling rate which are needed to be converted into analog.

• If the digital codes are directly converted into analog, it causes overloading on the player's amplifier and set up intermodulation distortion, also needs analog filters with tight specification (sharp transition from passband to stopband, and high attenuation in stop band).

Use of Multirate processing:

To avoid problems with analog filters, multirate filtering is employed.

Achieved by first increasing, by interpolation, the sampling rate of data by 4 to 176 kHz $(4 \times 44.1 = 176.4 \text{ kHz})$ before it can be applied to the DAC. The effects of this are:

- In time domain, the image frequencies are pushed to higher frequencies, making it it easier to filter them out, using a relatively simple lowpass filter
- Also, reduces the noise as the noise is spread over a wider bandwidth.

Example:

A digital audio system exploits oversampling techniques to relax requirements of the analog anti-imaging filter. The overall filter specifications for the system are given:

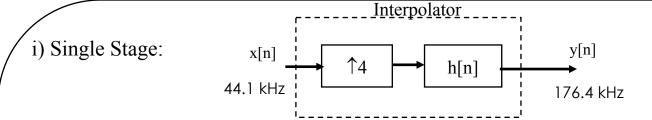
| baseband | 0-20 kHz |
|---------------------------|-----------|
| input sampling frequency | 44.1 kHz |
| output sampling frequency | 176.4 kHz |
| stopband attenuation | 40 dB |
| passband ripple | 1 dB |
| transition bandwidth | 2 kHz |
| stopband edge frequency | 22.05 kHz |

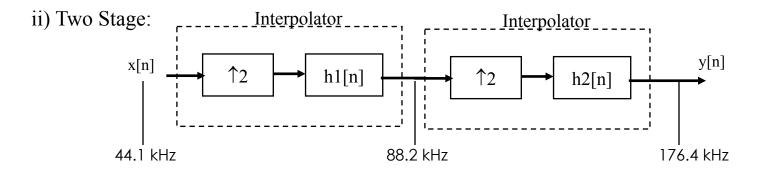
Design a suitable interpolator.

Solution: The interpolation factor
$$= \frac{\text{output sampling frequency}}{\text{input sampling frequency}} = \frac{176.4}{44.1} = 4$$

so the system can be implemented in:

- i) Single stage with factor = 4
- ii) Two stages with an interpolation factor of 2 in each stage.





| No. of Stages | Filter | Filter length N_i |
|------------------|----------------|---------------------|
| 1 | h[n] | 118 |
| 2 | h1[n] h2[n] | 39 6 |

We can see that by implementing a 2-stage interpolator we have simpler filters with filter lengths much smaller compared to the filter in single stage.